## MATH 210C: Mathematical Physics

Instructor: Michael Holst

## Spring Quarter 2016

## Homework Assignment #2

Due Date: NONE (just some suggested problems to look at to complement the lectures)

**Exercise 2.1.** (A Bit of Sets and Topology)

- 1. Define the open and closed balls in  $\mathbb{R}^n$ .
- 2. Give the definition of a topology that can be placed on a set M.
- 3. Give the definition of a topological space M.
- 4. What is the separation property that a Hausdorff topological space has.
- 5. Give the definition of a metric on a set.
- 6. Give the definition of a metric space.
- 7. Argue that a metric space is always a topological space.
- 8. Argue that a normed space is always a metric space.
- 9. Argue that an inner-product space is always a normed space.

**Exercise 2.2.** (*Maps on Toplogical Spaces*) Let  $F: M \to N$  be a map between two topological spaces M and N. Give definitions of the following properties of F:

- 1. injection (1-1)
- 2. surjection (onto)
- 3. bijection

Why does a map being bijective imply it has an inverse?

**Exercise 2.3.** (*Maps on Toplogical Spaces*) Let  $F: M \to N$  be a map between two topological spaces M and N. Give definitions of the following properties of F:

- 1. isomorphism
- 2. homeomorphism
- 3. differential homeomorphism
- 4. diffeomorphsm

## Exercise 2.4. (General Manifolds)

- 1. Explain what is meant by providing a set of charts ("patches" together with corresponding "local coordinate systems") for a set.
- 2. Give the definition of a differentiable n-manifold.
- 3. Give the definition of a  $C^{\infty}$  *n*-manifold.
- 4. Give the definition of an analytic *n*-manifold.

**Exercise 2.5.** (Vectors, Tangent spaces, Covectors, Cotangent spaces)

- 1. Define a (tangent) vector to a submanifold of  $\mathbb{R}^n$ , and to a general *n*-manifold  $M^n$ .
- 2. Define a (cotangent) covector to a submanifold of  $\mathbb{R}^n$ , and to a general *n*-manifold  $M^n$ .
- 3. Define the tangent space to an *n*-manifold  $M^n$  at the point *p*.
- 4. Define the cotangent space to an *n*-manifold  $M^n$  at the point *p*.

**Exercise 2.6.** (Implicitly Defined Submanifolds of  $\mathbb{R}^n$ ) Investigate the implicitly defined submanifold:

 $M=\{ \; x\in \mathbb{R}^3 \; | \; x_1^2+x_2^2-\!\! x_3^2=c \; \},$ 

in three distinct cases: c > 0, c < 0, c = 0. Are and/all of the three submanifolds? Do answers change if the origin is excluded? Draw all three level sets (loci) in one picture.

**Exercise 2.7.** (Submanifolds of  $\mathbb{R}^n$ ) Let  $M^n$  be a differentiable *n*-manifold, and let  $(U, x_U)$  be a chart (a patch U with a corresonding local coordinate system  $x_U = (x_U^1, \ldots, x_U^n)$ . Let us try to define a type of "global norm" on vector fields  $\bar{x}$  over  $M^n$  as:

$$\|\bar{x}\|^2 = \sum_{j=1}^n |x_u^i|^2.$$

Is this a "norm" in the sense that we have discussed? What is wrong?

**Exercise 2.8.** (Submanifolds of  $\mathbb{R}^n$  and  $M^n$ ) Let  $M^n$  be a differentiable submanifold of  $\mathbb{R}^N$  that does not contain the origin. Consider now  $f: M^n \to \mathbb{R}$  defined to be the function that assigns to each point of  $M^n$  the square of its distance from the origin. Using local coordinates  $(u^1, \ldots, u^n)$ , show that a point  $p \in M^n$  is a critical point for this distance function if and only of the position vector to this point is normal to the submanifold  $M^n$ .

**Exercise 2.9.** (Vector fields and Flows in  $\mathbb{R}^n$  and  $M^n$ ) Consider the vector field on  $\mathbb{R}$  defined as  $v(x) = x^2(d/dx)$ . I.e., v(x) moves  $x^2$  distance in the coordinate direction d/dx. Find the flow  $\phi_t(p)$  corresponding to this vector field by solving the differential equation

$$\frac{dx}{dt} = x^2, \qquad , x(0) = p.$$

Now define the open interval containing p as  $U_p = (1/2, 3/2)$ . Find the largest  $\epsilon$  so that  $\phi: U_p \times (-\epsilon, \epsilon) \to \mathbb{R}$  is well-defined. I.e., find the largest t for which the integral curve  $\phi_t(p)$  is well-defined for all  $p \in U_p$ .

**Exercise 2.10.** (*Covectors in*  $\mathbb{R}^n$  and  $M^n$ ) If v is a vector and  $\alpha$  is a covector, compute (directly in coordinates) that

$$\sum_{i=1}^{n} a_i^V v_V^i = \sum_{i=1}^{n} a_i^U v_U^i.$$

I.e., you have shown that this quantity is invariant under coordinate transformation.

**Exercise 2.11.** (*Tensors and Metrics in*  $\mathbb{R}^n$  and  $M^n$ ) Let x, y, z be the standard orthogonal cartesian coordinates in  $\mathbb{R}^3$ , the basis vectors for which we denote as  $\partial_x$ ,  $\partial_y$ , and  $\partial_z$ . Let  $u^1 = r$ ,  $u^2 = \theta$ ,  $u^3 = \phi$  be spherical coordinates, with corresponding basis vectors  $\partial_r$ ,  $\partial_{\theta}$ , and  $\partial_{\phi}$ . Recall that the relationship between (x, y, z) and  $(r, \theta, \phi)$  is:

$$\begin{aligned} x &= r \, \sin \theta \, \cos \phi, \\ y &= r \, \sin \theta \, \sin \phi, \\ z &= r \, \cos \theta. \end{aligned}$$

1. Use the chain rule to compute the metric tensor components for spherical coordinates:

$$g_{r\theta} = g_{12} = \langle \partial_r, \partial_\theta \rangle, \dots$$

- 2. Confirm that the basis functions  $\partial_r$ ,  $\partial_{\theta}$ , and  $\partial_{\phi}$  are mutually orthogonal just as as  $\partial_x$ ,  $\partial_y$ , and  $\partial_z$  are mutually orthogonal, BUT they are NOT unit length.
- 3. Compute the coefficients of the gradient with respect to spherical coordinates:

$$\nabla f = (\nabla f)^r \partial_r + (\nabla f)^\theta \partial_\theta + (\nabla f)^\phi \partial_\phi.$$

4. Finally, coefficients of the Laplacean with respect to spherical coordinates: (This one is actually not that easy.)

$$\nabla^2 f = \nabla \cdot (\nabla f)$$

**Exercise 2.12.** (2-Tensors and Metrics in  $\mathbb{R}^n$  and  $M^n$ ) Repeat Problem 2.11 but for cylindrical coordinates in  $\mathbb{R}^3$ .

**Exercise 2.13.** (2-Tensors and Metrics in  $\mathbb{R}^n$  and  $M^n$ ) Repeat Problem 2.11 but for polar coordinates in  $\mathbb{R}^2$ .

**Exercise 2.14.** (Tangent and Cotangent Spaces and Bundles) Let  $F: M^n \to W^r$  and  $G: W^r \to V^s$  be smooth maps, where  $M^n, W^r, V^s$  are differentiable manifolds. Let (x, y, z) be local coordinates near  $p \in M^n$ ,  $F(p) \in W^r$ , and  $G(F(p)) \in V^s$ , respectively, and consider the composite map  $G \circ F: M^n \to V^s$ .

1. Using bases  $\partial_x, \partial_y, \partial_z$ , show that the differentials obey:

$$(G \circ F)_* = G_* \circ F_*.$$

2. Using bases dx, dy, dz, show that the differentials obey:

$$(G \circ F)^* = G^* \circ F^*.$$

**Exercise 2.15.** (*General Tensors and Exterior Forms*) Let  $A: E \to E$  be a linear transformation on a vector space E.

- 1. Show that the trace  $tr(A) = \sum_{i=1}^{n} A_i^i$  is a true scalar (independent of coordinate transformation) by using the basic transformation properties of mixed tensors. Here  $A_j^i$  are the mixed components of A with respect to both the vector space E and the dual space  $E^*$ .
- 2. What about the similar quantity computed with respect to only one of the bases, e.g.,  $\sum_{i=1}^{n} A_{ii}$ ? Is this a scalar?

**Exercise 2.16.** (*General Tensors and Exterior Forms*) Let  $\bar{v} = v^i \partial_i$  (summation convention) be a (contravariant) vector field on a differentiable manifold  $M^n$ .

1. Show that  $v_j = g_{ji}v^i$  are the components of a corresponding covector representation of  $\bar{v}$ , by showing that the required transformation properties hold. You will need to use the chain rule:

$$\frac{\partial}{\partial y^i} \left( \frac{\partial y^j}{\partial x^k} \right) = \sum_{r=1}^n \left( \frac{\partial^2 y^j}{\partial x^r \partial x^k} \right) \left( \frac{\partial x^r}{\partial y^i} \right).$$

- 2. Does  $\partial_j v^i$  produce a tensor?
- 3. Does  $(\partial_i v^j \partial_j v^i)$  produce a tensor?