

2.1.1

(a)
$$\left[\begin{array}{cc|c} 2 & -3 & 2 \\ 5 & -6 & 8 \end{array} \right]$$

subtract $2.5 \times$ row 1 from row 2

$$\Rightarrow \left[\begin{array}{cc|c} 2 & -3 & 2 \\ 0 & 1.5 & 3 \end{array} \right]$$

$$\Rightarrow \begin{cases} 2x - 3y = 2 \\ 1.5y = 3 \end{cases} \Rightarrow \begin{cases} x = 4 \\ y = 2 \end{cases}$$

(b)
$$\left[\begin{array}{cc|c} 1 & 2 & -1 \\ 2 & 3 & 1 \end{array} \right]$$

subtract $2 \times$ row 1 from row 2

$$\Rightarrow \left[\begin{array}{cc|c} 1 & 2 & -1 \\ 0 & -1 & 3 \end{array} \right]$$

$$\Rightarrow \begin{cases} x + 2y = -1 \\ -y = 3 \end{cases} \Rightarrow \begin{cases} x = 5 \\ y = -3 \end{cases}$$

2.1.3

(a)
$$\begin{cases} 3x - 4y + 5z = 2 & \dots (1) \\ 3y - 4z = -1 & \dots (2) \\ 5z = 5 & \dots (3) \end{cases}$$

$$\Rightarrow z = 1 \Rightarrow \begin{array}{l} \text{Plug } z=1 \text{ into (2)} \\ \text{we have } y=1 \end{array} \Rightarrow \begin{array}{l} \text{Plug } z=1, y=1 \\ \text{into (1)} \\ \text{we have } x = \frac{1}{3} \end{array}$$

2.2.1

(a) $\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$

(2)

subtracts $3 \times$ row 1 from row 2

We have $U = \begin{bmatrix} 1 & 2 \\ 0 & -2 \end{bmatrix}$

$$L = \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix}$$

(b) $\begin{bmatrix} 1 & 3 \\ 2 & 2 \end{bmatrix}$

Subtract $2 \times$ row 1 from row 2

We have $U = \begin{bmatrix} 1 & 3 \\ 0 & -4 \end{bmatrix}$

$$L = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$$

2.3.2

(a) $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$

step 1: $\|A\|_{\infty} = 7$

step 2: Find A^{-1} , solve $\begin{bmatrix} 1 & 2 & | & 1 \\ 3 & 4 & | & 0 \end{bmatrix} \Rightarrow$ solution is $\begin{bmatrix} -2 \\ 3/2 \end{bmatrix}$

solve $\begin{bmatrix} 1 & 2 & | & 0 \\ 3 & 4 & | & 1 \end{bmatrix} \Rightarrow$ solution is $\begin{bmatrix} 1 \\ -1/2 \end{bmatrix}$

then $A^{-1} = \begin{bmatrix} -2 & 1 \\ 3/2 & -1/2 \end{bmatrix}$

step 3: $\|A^{-1}\|_{\infty} = 3$

step 4: $\text{cond}(A) = \|A\|_{\infty} \cdot \|A^{-1}\|_{\infty} = 21$

$$\text{or (b) } A = \begin{bmatrix} 1 & 2.01 \\ 3 & 6 \end{bmatrix}$$

(3)

$$\text{step 1: } \|A\|_{\infty} = 9$$

$$\text{step 2: Find } A^{-1}, \text{ solve } \begin{bmatrix} 1 & 2.01 & | & 1 \\ 3 & 6 & | & 0 \end{bmatrix} \Rightarrow \text{solution is } \begin{bmatrix} -200 \\ 100 \end{bmatrix}$$

$$\text{solve } \begin{bmatrix} 1 & 2.01 & | & 0 \\ 3 & 6 & | & 1 \end{bmatrix} \Rightarrow \text{solution is } \begin{bmatrix} \frac{100}{3} \\ -\frac{100}{3} \end{bmatrix}$$

$$\Rightarrow A^{-1} = \begin{bmatrix} -200 & 67 \\ 100 & -100/3 \end{bmatrix}$$

$$\text{step 3: } \|A^{-1}\|_{\infty} = 267$$

$$\text{step 4: } \text{Cond}(A) = \|A\|_{\infty} \|A^{-1}\|_{\infty} = 2403$$

2.3.8 ca) Matrix is $A = \begin{bmatrix} 1 & 1 \\ 1+\epsilon & 1 \end{bmatrix}, \epsilon > 0.$

$$\text{step 1: } \|A\|_{\infty} = 2 + \epsilon$$

$$\text{step 2: Find } A^{-1}, \text{ solve } \begin{bmatrix} 1 & 1 & | & 1 \\ 1+\epsilon & 1 & | & 0 \end{bmatrix} \Rightarrow \text{solu is } \begin{bmatrix} -\frac{1}{\epsilon} \\ \frac{1+\epsilon}{\epsilon} \end{bmatrix}$$

$$\text{solve } \begin{bmatrix} 1 & 1 & | & 0 \\ 1+\epsilon & 1 & | & 1 \end{bmatrix} \Rightarrow \text{solu is } \begin{bmatrix} \frac{1}{\epsilon} \\ -\frac{1}{\epsilon} \end{bmatrix}$$

$$\Rightarrow A^{-1} = \begin{bmatrix} -\frac{1}{\epsilon} & \frac{1}{\epsilon} \\ \frac{1+\epsilon}{\epsilon} & -\frac{1}{\epsilon} \end{bmatrix}$$

$$\text{step 3: } \|A^{-1}\|_{\infty} = \frac{2+\epsilon}{\epsilon}$$

$$\text{step 4: } \text{Cond}(A) = \|A\|_{\infty} \|A^{-1}\|_{\infty} = \frac{(2+\epsilon)^2}{\epsilon}$$

(b) step 1: Find relative forward error

(4)

The exact solu $X = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$$\Rightarrow \|X - X_{all}\|_{\infty} = 2 + \epsilon$$

$$\|X\|_{\infty} = 1$$

\Rightarrow relative forward error is $2 + \epsilon$.

step 2: Find relative backward error.

$$r = b - AXa = \begin{bmatrix} -\epsilon \\ \epsilon \end{bmatrix}, \text{ and } \|b\|_{\infty} = 2 + \epsilon$$

$$\Rightarrow \text{relative backward error is } \frac{\|r\|_{\infty}}{\|b\|_{\infty}} = \frac{\epsilon}{2 + \epsilon}$$

step 3: The error magnification factor

$$= \frac{RFE}{RBE} = \frac{(2 + \epsilon)^2}{\epsilon}$$

2.4.3 (b).

step 1: Eliminate ~~the~~ column 1.

$$\text{Exchange Row 1 and 2, } \Rightarrow P = \begin{bmatrix} 0 & 1 & 6 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 6 & 3 & 4 \\ 3 & 1 & 2 \\ 3 & 1 & 5 \end{bmatrix} \Rightarrow \begin{bmatrix} 6 & 3 & 4 \\ -\frac{1}{2} & -\frac{1}{2} & 0 \\ -\frac{1}{2} & -\frac{1}{2} & 3 \end{bmatrix}$$

step 2: Eliminate column 2.

No Row exchange needed

$$\begin{bmatrix} 6 & 3 & 4 \\ -\frac{1}{2} & -\frac{1}{2} & 0 \\ -\frac{1}{2} & -\frac{1}{2} & 3 \end{bmatrix} = \begin{bmatrix} 6 & 3 & 4 \\ -\frac{1}{2} & -0.5 & 0 \\ -\frac{1}{2} & 1 & 3 \end{bmatrix}$$

Then, we have

$$P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix},$$

$$L = \begin{bmatrix} 1 & & \\ \frac{1}{2} & 1 & \\ \frac{1}{2} & & 1 \end{bmatrix}$$

(5)

$$U = \begin{bmatrix} 6 & 3 & 4 \\ & -0.5 & 0 \\ & & 3 \end{bmatrix}$$

step 3. Solve $LC = Pb$

By back substitution $\begin{bmatrix} 1 & & \\ \frac{1}{2} & 1 & \\ \frac{1}{2} & & 1 \end{bmatrix} \cdot \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$

$$\Rightarrow C = \begin{bmatrix} \frac{1}{2} \\ 3 \\ 3 \end{bmatrix}$$

step 4. Solve $UX = C$

By back substitution $\begin{bmatrix} 6 & 3 & 4 \\ & -0.5 & 0 \\ & & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ 3 \end{bmatrix}$

$$\Rightarrow X = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

2.5.1

c) Jacobi iteration

$$X_{k+1} = D^{-1}(cb - (L+U)X_k) \dots \dots (1)$$

where $D = \begin{bmatrix} 3 & & \\ & 3 & \\ & & 3 \end{bmatrix}$, $L = \begin{bmatrix} 0 & & \\ 1 & 0 & \\ 1 & 1 & 0 \end{bmatrix}$, $U = \begin{bmatrix} 0 & 1 & 1 \\ & 0 & 0 \\ & & 0 \end{bmatrix}$

$$b = \begin{bmatrix} 6 \\ 3 \\ 5 \end{bmatrix}, X_0 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

\Rightarrow ~~Plug~~ Plug everything into (1)

One has $X_1 = \begin{bmatrix} 2 \\ 1 \\ \frac{5}{3} \end{bmatrix}$, $X_2 = \begin{bmatrix} \frac{10}{9} \\ -\frac{2}{9} \\ \frac{2}{3} \end{bmatrix}$.

Gauss-Seidal iteration

(6)

$$(D+L)X_{k+1} = b - UX_k \quad \dots (2)$$

Plug D, L, U, b into (2)

We have $X_1 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$, $X_2 = \begin{bmatrix} 1.5926 \\ 0.1728 \\ 0.8889 \end{bmatrix}$.

$$\begin{bmatrix} 2 \\ 1/3 \\ 8/9 \end{bmatrix}$$

2.6.1

(a) $\begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix} = A$

Obviously, $A^T = A$, A is symmetric.

And, $x^T A x = x_1^2 + 3x_2^2 > 0, \forall x \neq 0$

thus, A is symmetric pos-def.

(c) $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$

Obviously, $A^T = A$, A is symmetric.

And, $x^T A x = x_1^2 + 2x_2^2 + 3x_3^2 > 0, \forall x \neq 0$,

thus A is sym pos-def.

2.6.13

$$\text{ca). } A = \begin{bmatrix} 1 & 2 \\ 2 & 5 \end{bmatrix}, b = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{Let } x_0 = \begin{bmatrix} 0 \\ 6 \end{bmatrix}$$

$$\Rightarrow d_0 = r_0 = b - Ax_0 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{step 1: } \alpha_0 = \frac{r_0^T r_0}{d_0^T A d_0} = \frac{1}{5}$$

$$x_1 = x_0 + \alpha_0 d_0 = \begin{bmatrix} \frac{1}{5} \\ \frac{1}{5} \end{bmatrix}$$

$$r_1 = r_0 - \alpha_0 A d_0 = \begin{bmatrix} \frac{3}{5} \\ -\frac{3}{5} \end{bmatrix}$$

$$\beta_0 = \frac{r_1^T r_1}{r_0^T r_0} = \frac{4}{25}$$

$$d_1 = r_1 + \beta_0 d_0 = \begin{bmatrix} \frac{14}{25} \\ -\frac{6}{25} \end{bmatrix}$$

$$\text{step 2: } \alpha_1 = \frac{r_1^T r_1}{d_1^T A d_1} = 5$$

$$x_2 = x_1 + \alpha_1 d_1 = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$

$$r_2 = r_1 - \alpha_1 d_1 = 0 \quad \text{stop.}$$

$$\text{Solu is } x = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$

(7)

2.7.1

(a) $F(u, v) = (u^3, uv^3)$

(8)

$$J = \begin{bmatrix} \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} \\ \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} \end{bmatrix} = \begin{bmatrix} 3u^2 & 0 \\ v^3 & 3uv^2 \end{bmatrix}$$

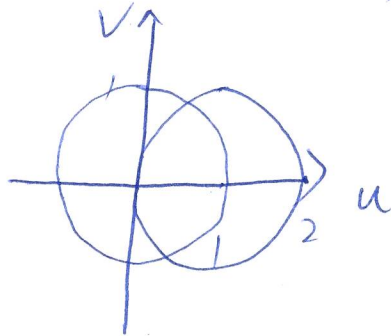
(d) $F(u, v, w) = (u^2 + v - w^2, \sin uvw, uvw^4)$

$$J = \begin{bmatrix} \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} & \frac{\partial f_1}{\partial w} \\ \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} & \frac{\partial f_2}{\partial w} \\ \frac{\partial f_3}{\partial u} & \frac{\partial f_3}{\partial v} & \frac{\partial f_3}{\partial w} \end{bmatrix} = \begin{bmatrix} 2u & 1 & -2w \\ vw \cos uvw & uvw \cos uvw & uv \cos uvw \\ vw^4 & uw^4 & 4uvw^3 \end{bmatrix}$$

2.7.3

(a) $\begin{cases} u^2 + v^2 = 1 \dots (1) \\ (u-1)^2 + v^2 = 1 \dots (2) \end{cases}$

Graph:

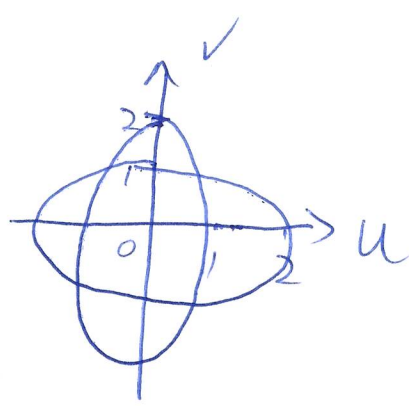


From (2), we have $v^2 = 1 - (u-1)^2$, plug it into (1),

One has $u^2 - (u-1)^2 = 0 \Rightarrow u-1 = \frac{-u}{1} \Rightarrow u = \frac{1}{2}$

$\Rightarrow v = \pm \frac{\sqrt{3}}{2} \Rightarrow$ Solu are $\begin{cases} \frac{1}{2} \\ \frac{\sqrt{3}}{2} \end{cases}, \begin{cases} \frac{1}{2} \\ -\frac{\sqrt{3}}{2} \end{cases}$

$$c_b) \begin{cases} u^2 + 4v^2 = 4 \dots (1) \\ 4u^2 + v^2 = 4 \dots (2) \text{ Graph.} \end{cases}$$



(9)

From (2), one has $v^2 = 4 - 4u^2$
 substitute it into (1).

$$u^2 + 16 - 16u^2 = 4$$

$$\Rightarrow u = \pm \frac{2}{\sqrt{5}}, \Rightarrow v = \pm \frac{2}{\sqrt{5}}$$

$$\Rightarrow \text{Solu are } \begin{cases} \frac{2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{cases}, \begin{cases} -\frac{2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{cases}, \begin{cases} \frac{2}{\sqrt{5}} \\ -\frac{2}{\sqrt{5}} \end{cases}, \begin{cases} -\frac{2}{\sqrt{5}} \\ -\frac{2}{\sqrt{5}} \end{cases}$$

2.7.4

$$c_a) J = \begin{bmatrix} \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} \\ \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} \end{bmatrix} = \begin{bmatrix} 2u & 2v \\ 2(u-1) & 2v \end{bmatrix}, F = \begin{cases} u^2 + v^2 - 1 \\ (u-1)^2 + v^2 - 1 \end{cases}$$

step 1. $J(x_0)h = -F(x_0)$

$$\Rightarrow \begin{bmatrix} 2 & 2 \\ 0 & 2 \end{bmatrix} h = - \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\Rightarrow h = \begin{bmatrix} -\frac{1}{2} & 0 \end{bmatrix}^T \Rightarrow X_1 = X_0 + h = \begin{bmatrix} \frac{1}{2} & 1 \end{bmatrix}^T$$

step 2. $J(x_1)h = -F(x_1)$

$$\Rightarrow \begin{bmatrix} 1 & 2 \\ -1 & 2 \end{bmatrix} h = - \begin{bmatrix} \frac{1}{4} \\ \frac{1}{4} \end{bmatrix}$$

$$\Rightarrow h = \begin{bmatrix} 0 & -\frac{1}{8} \end{bmatrix}^T \Rightarrow X_2 = X_1 + h = \begin{bmatrix} \frac{1}{2} & \frac{7}{8} \end{bmatrix}^T$$

$$c_b) J = \begin{bmatrix} 2u & 8v \\ 8u & 2v \end{bmatrix}, F = \begin{cases} u^2 + 4v^2 - 4 \\ 4u^2 + v^2 - 4 \end{cases}$$

step 1. $J(x_0)h = -F(x_0)$

$$\Rightarrow \begin{bmatrix} 2 & 8 \\ 8 & 2 \end{bmatrix} h = - \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\Rightarrow h = \begin{bmatrix} -\frac{1}{10} & -\frac{1}{10} \end{bmatrix}^T \Rightarrow X_1 = X_0 + h = \begin{bmatrix} \frac{9}{10} & \frac{9}{10} \end{bmatrix}^T$$

step 2. $J(x_1)h = -F(x_1)$

$$\Rightarrow \begin{bmatrix} \frac{2}{5} & \frac{36}{5} \\ \frac{36}{5} & \frac{2}{5} \end{bmatrix} h = - \begin{bmatrix} \frac{1}{20} \\ \frac{1}{20} \end{bmatrix}$$

$$\Rightarrow h = \begin{bmatrix} -\frac{1}{180} & -\frac{1}{180} \end{bmatrix}^T$$

$$\Rightarrow X_2 = X_1 + h = \begin{bmatrix} \frac{161}{180} & \frac{161}{180} \end{bmatrix}^T$$