A Spectral Approach to the Relativistic Inverse Stellar Structure Problem

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26th Pacific Coast Gravity Conference UC San Diego 27 March 2010

• What is the relativistic inverse stellar structure problem (SSP⁻¹)?

• Can spectral methods provide a more effective way to solve it?

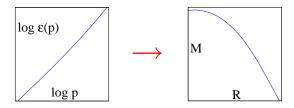
Relativistic Stellar Structure Problem (SSP)

• Given an equation of state, $\epsilon = \epsilon(p)$, solve Einstein's equations,

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \frac{dp}{dr} = -(\epsilon + p) \frac{m + 4\pi r^3 p}{r(r - 2m)},$$

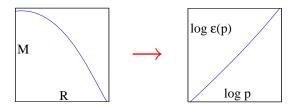
to determine the structures of relativistic stars.

- Find the radius p(R) = 0 and mass M = m(R) for each star.
- SSP can be thought of as a map from the equation of state $\epsilon = \epsilon(p)$ to the M-R curve $\{R(p_c), M(p_c)\}$.



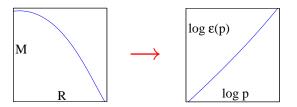
Relativistic Inverse Stellar Structure Problem (SSP⁻¹)

- When the equation of state is well understood as in white dwarf stars – the standard stellar structure problem is useful.
- When the equation of state is poorly known as in neutron stars the inverse stellar structure problem may be more interesting.

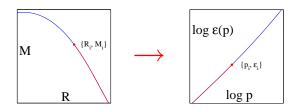


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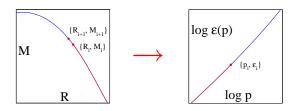
- When the equation of state is well understood as in white dwarf stars – the standard stellar structure problem is useful.
- When the equation of state is poorly known as in neutron stars the inverse stellar structure problem may be more interesting.
- SSP⁻¹ finds the equation of state ε = ε(p) from a given mass-radius curve.
- SSP⁻¹ can be thought of as a map from the M-R curve $\{R(p_c), M(p_c)\}$ to the equation of state $\epsilon = \epsilon(p)$.



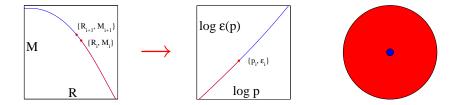
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- Assume the complete M-R curve is known.



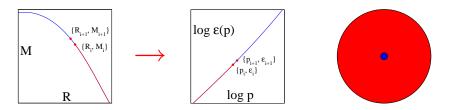
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- Integrate Einstein's equations through the outer parts of the star, to determine the mass and radius, {r_{i+1}, m_{i+1}}, of the core.
- Use a power series solution of Einstein's equations in the core to determine the central pressure and density, {p_{i+1}, ε_{i+1}}.



Can the Standard Solution to SSP⁻¹ be Improved?

- Standard solution to the relativistic SSP⁻¹ finds the equation of state, ε = ε(p), represented as a table: {p_i, ε_i} for i = 1, ..., N.
- Standard solution has several weaknesses:
 - Solution converges (slowly) with the number of points, as N^{-p} .
 - Each equation of state point found, {p_i, ε_i}, requires the knowledge of a separate M-R curve point, {R_i, M_i}.
 - Accurate M-R curve points $\{R_i, M_i\}$ for neutron stars are scarce.

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- Spectral numerical methods typically converge more rapidly, and represent functions more efficiently than finite difference methods.
- Can spectral methods provide better solutions to the SSP⁻¹?

• Assume the equation of state can be written in the form $\epsilon = \epsilon(\mathbf{p}, \lambda_{\alpha})$, where the λ_{α} are a set of parameters.

For example, the equation of state could be written as a spectral expansion, $\epsilon = \epsilon(p, \lambda_{\alpha}) = \sum_{\alpha} \lambda_{\alpha} \Phi_{\alpha}(p)$, where the $\Phi_{\alpha}(p)$ are spectral basis functions.

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- Given a set of points from the "real" M-R curve, {*R_i*, *M_i*}, choose the parameters λ_α and *p_i* that minimize the difference measure:

$$\Delta_{MR}^{2} = \frac{1}{N} \sum_{i=1}^{N} \left\{ \left[\log \left(\frac{R(p_{i}, \lambda_{\alpha})}{R_{i}} \right) \right]^{2} + \left[\log \left(\frac{M(p_{i}, \lambda_{\alpha})}{M_{i}} \right) \right]^{2} \right\}$$

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• Resulting λ_{α} for $\alpha = 1, ..., N$ determine an equation of state, $\epsilon = \epsilon(\mathbf{p}, \lambda_{\alpha})$, that provides an approximate solution of SSP⁻¹.

Faithful Spectral Expansions of the Equation of State

- Physical equations of state, ε = ε(p), are positive monotonic increasing functions. These do not form a vector space.
- The representation, $\epsilon = \epsilon(p, \lambda_{\alpha}) = \sum_{\alpha} \lambda_{\alpha} \Phi_{\alpha}(p)$, is not faithful.
- Faithful here means that every choice of λ_{α} corresponds to a possible physical equation of state, and every equation of state can be represented by such an expansion.

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- Faithful spectral expansions of the adiabatic index do exist:

$$\Gamma(p) = \frac{\epsilon c^2 + p}{pc^2} \frac{dp}{d\epsilon} = \exp\left[\sum_{\alpha} \gamma_{\alpha} \Phi_{\alpha}(p)\right]$$

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Every equation of state is determined by the adiabatic index Γ(p):

$$\mu(p) = \exp\left[\int_{p_0}^{p} \frac{dp'}{p'\Gamma(p')}\right],$$

$$\epsilon(p) = \frac{\epsilon_0}{\mu(p)} + \frac{1}{\mu(p)}\int_{p_0}^{p} \frac{\mu(p')}{c^2\Gamma(p')}dp'.$$

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$$\Delta_{\epsilon}^{2} = \frac{1}{N} \sum_{i=1}^{N} \left\{ \left[\log \left(\frac{\epsilon(\boldsymbol{p}_{i}, \gamma_{\alpha})}{\epsilon_{i}} \right) \right]^{2} \right\}$$

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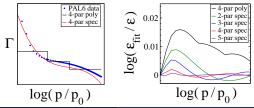
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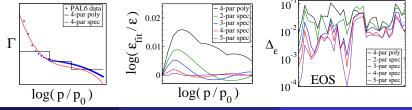
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- Next step is to test this spectral approach by finding the approximate solution to SSP⁻¹ for realistic neutron star models.
- Choose points {*R_i*, *M_i*} from realistic neutron star models, then fix the spectral expansion coefficients γ_α by minimizing,

$$\Delta_{MR}^2 = \frac{1}{N} \sum_{i=1}^{N} \left\{ \left[\log \left(\frac{M(p_i, \gamma_\alpha)}{M_i} \right) \right]^2 + \left[\log \left(\frac{R(p_i, \gamma_\alpha)}{R_i} \right) \right]^2 \right\}.$$

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• Finally evaluate Δ_{ϵ} , $\Delta_{\epsilon}^{2} = \frac{1}{N} \sum_{i=1}^{N} \left\{ \left[\log \left(\frac{\epsilon(p_{i}, \gamma_{\alpha})}{\epsilon_{i}} \right) \right]^{2} \right\}$ to determine how well the spectral expansion $\epsilon = \epsilon(p, \gamma_{\alpha})$,

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- The End.