Solving Einstein's Equation Numerically IV

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What Do We Mean By Hyperbolic?

- We have argued that Einstein's equation is "manifestly hyperbolic" because its principal part is the same as the scalar wave equation.
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- From a pragmatic physicist's point of view, hyperbolic means anything that acts like the wave equation, i.e. any system of equations having a well posed initial-boundary value problem.
- Symmetric hyperbolic systems are one class of equations for which suitable well-posedness theorems exist, and which are general enough to include Einstein's equations together with most of the other dynamical field equations used by physicists.

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- From a pragmatic physicist's point of view, hyperbolic means anything that acts like the wave equation, i.e. any system of equations having a well posed initial-boundary value problem.
- Symmetric hyperbolic systems are one class of equations for which suitable well-posedness theorems exist, and which are general enough to include Einstein's equations together with most of the other dynamical field equations used by physicists.
- Evolution equations of the form,

 $\partial_t u^{\alpha} + A^{k\,\alpha}{}_{\beta}(u, x, t)\partial_k u^{\beta} = F^{\alpha}(u, x, t),$ for a collection of dynamical fields u^{α} , are called symmetric hyperbolic if there exists a positive definite $S_{\alpha\beta}$ having the property that $S_{\alpha\gamma}A^{k\,\gamma}{}_{\beta} \equiv A^k_{\alpha\beta} = A^k_{\beta\alpha}.$

Example: Scalar Wave Equation

 Consider the scalar wave equation in flat space, expressed in terms of arbitrary spatial coordinates:

$$0 = -\partial_t^2 \psi + \nabla^k \nabla_k \psi = -\partial_t^2 \psi + g^{k\ell} (\partial_k \partial_\ell \psi - \Gamma_{k\ell}^n \partial_n \psi).$$

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Define the first-order dynamical fields, u^α = {ψ, Π, Φ_k}, which satisfy the following evolution equations:

 $\partial_t \psi = -\Pi, \qquad \partial_t \Pi + \nabla^k \Phi_k = 0, \qquad \partial_t \Phi_k + \nabla_k \Pi = 0.$

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 $\partial_t \psi = -\Pi, \qquad \partial_t \Pi + \nabla^k \Phi_k = 0, \qquad \partial_t \Phi_k + \nabla_k \Pi = 0.$

• The principal part of this system, $\partial_t u^{\alpha} + A^{k \alpha}{}_{\beta} \partial_k u^{\beta} \simeq 0$, is given:

Example: Scalar Wave Equation II

• The symmetrizer for the first-order scalar field system is:

 $dS^2 = S_{\alpha\beta} du^{\alpha} du^{\beta} = \Lambda^2 d\psi^2 + d\Pi^2 + g^{mn} d\Phi_m d\Phi_n.$

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$$dS^2 = S_{\alpha\beta} du^{\alpha} du^{\beta} = \Lambda^2 d\psi^2 + d\Pi^2 + g^{mn} d\Phi_m d\Phi_n.$$

• Check the symmetrization of the characteristic matrices:

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- We denote the principal part of these first order systems using the notation ∂_tu^α + A^{k α}_β∂_ku^β ≃ 0. The principal part of the first-order GH Einstein equations can be written as:

 $\begin{array}{lll} \partial_t \psi_{ab} - N^k \partial_k \psi_{ab} &=& -N \Pi_{ab}, \\ \partial_t \Pi_{ab} - N^k \partial_k \Pi_{ab} + N g^{ki} \partial_k \Phi_{iab} &\simeq& 0, \\ \partial_t \Phi_{iab} - N^k \partial_k \Phi_{iab} + N \partial_i \Pi_{ab} &\simeq& 0, \end{array}$ where $\Phi_{kab} = \partial_k \psi_{ab}.$

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- We denote the principal part of these first order systems using the notation $\partial_t u^{\alpha} + A^{k\,\alpha}{}_{\beta}\partial_k u^{\beta} \simeq 0$. The principal part of the first-order GH Einstein equations can be written as:

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where $\Phi_{kab} = \partial_k \psi_{ab}$.

- This system has two immediate problems:
 - This system has new constraints, $C_{kab} = \partial_k \psi_{ab} \Phi_{kab}$, that tend to grow exponentially during numerical evolutions.
 - This system is not linearly degenerate, so it is possible (likely?) that shocks will develop (e.g. the components that determine the shift evolution have the form $\partial_t N^i N^k \partial_k N^i \simeq 0$).

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A 'New' Generalized Harmonic Evolution System

 We can correct these problems by adding additional multiples of the constraints to the evolution system:

 $\partial_t \psi_{ab} - (1 + \gamma_1) N^k \partial_k \psi_{ab} = -N \Pi_{ab} - \gamma_1 N^k \Phi_{kab},$ $\partial_t \Pi_{ab} - N^k \partial_k \Pi_{ab} + N g^{ki} \partial_k \Phi_{iab} - \gamma_1 \gamma_2 N^k \partial_k \psi_{ab} \simeq -\gamma_1 \gamma_2 N^k \Phi_{kab},$ $\partial_t \Phi_{iab} - N^k \partial_k \Phi_{iab} + N \partial_i \Pi_{ab} - \gamma_2 N \partial_i \psi_{ab} \simeq -\gamma_2 N \Phi_{iab}.$

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- This 'new' generalized-harmonic evolution system has several nice properties:
 - This system is symmetric hyperbolic for all values of γ_1 and γ_2 .
 - The Φ_{iab} evolution equation can be written in the form, $\partial_t C_{iab} - N^k \partial_k C_{iab} \simeq -\gamma_2 N C_{iab}$, so the new constraints are damped when $\gamma_2 > 0$.
 - This system is linearly degenerate for $\gamma_1 = -1$ (and so shocks should not form from smooth initial data).

Constraint Evolution for the New GH System

• The evolution of the constraints,

 $c^{A} = \{C_{a}, C_{kab}, \mathcal{F}_{a} \approx t^{c} \partial_{c} C_{a}, C_{ka} \approx \partial_{k} C_{a}, C_{klab} = \partial_{[k} C_{l]ab}\}$ are determined by the evolution of the fields $u^{\alpha} = \{\psi_{ab}, \Pi_{ab}, \Phi_{kab}\}$:

$$\partial_t c^A + A^{kA}{}_B(u)\partial_k c^B = F^A{}_B(u,\partial u) c^B.$$

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$$\partial_t c^A + A^{kA}{}_B(u)\partial_k c^B = F^A{}_B(u,\partial u) c^B$$

 This constraint evolution system is symmetric hyperbolic with principal part:

 $\begin{array}{rcl} \partial_t \mathcal{C}_a &\simeq & \mathbf{0}, \\ \partial_t \mathcal{F}_a - \mathbf{N}^k \partial_k \mathcal{F}_a - \mathbf{N} g^{ij} \partial_i \mathcal{C}_{ja} &\simeq & \mathbf{0}, \\ \partial_t \mathcal{C}_{ia} - \mathbf{N}^k \partial_k \mathcal{C}_{ia} - \mathbf{N} \partial_i \mathcal{F}_a &\simeq & \mathbf{0}, \\ \partial_t \mathcal{C}_{iab} - (\mathbf{1} + \gamma_1) \mathbf{N}^k \partial_k \mathcal{C}_{iab} &\simeq & \mathbf{0}, \\ \partial_t \mathcal{C}_{ijab} - \mathbf{N}^k \partial_k \mathcal{C}_{ijab} &\simeq & \mathbf{0}. \end{array}$

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 An analysis of this system shows that all of the constraints are damped in the WKB limit when γ₀ > 0 and γ₂ > 0. So, this system has constraint suppression properties that are similar to those of the Pretorius (and Gundlach, et al.) system.

Numerical Tests of the New GH System

- 3D numerical evolutions of static black-hole spacetimes illustrate the constraint damping properties of our GH evolution system.
- These evolutions are stable and convergent when $\gamma_0 = \gamma_2 = 1$.



• The boundary conditions used for this simple test problem freeze the incoming characteristic fields to their initial values.

We impose boundary conditions on first-order hyperbolic evolution systems, ∂_tu^α + A^{kα}_β(u)∂_ku^β = F^α(u) in the following way (where in our case u^α = {ψ_{ab}, Π_{ab}, Φ_{kab}}):

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- We first find the eigenvectors of the characteristic matrix n_kA^{k α}_β at each boundary point:

$$\boldsymbol{e}^{\hat{lpha}}{}_{\alpha} \boldsymbol{n}_{k} \boldsymbol{A}^{k \, \alpha}{}_{\beta} = \boldsymbol{v}_{(\hat{lpha})} \boldsymbol{e}^{\hat{lpha}}{}_{\beta},$$

where n_k is the (spacelike) outward directed unit normal; and then define the characteristic fields:

$$u^{\hat{lpha}}={\it e}^{\hat{lpha}}{}_{lpha}u^{lpha}.$$

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Finally we impose a boundary condition on each incoming characteristic field (*i.e.* every field with v_(â) < 0), and impose no condition on any outgoing field (*i.e.* any field with v_(â) ≥ 0).

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- Finally we impose a boundary condition on each incoming characteristic field (*i.e.* every field with v_(â) < 0), and impose no condition on any outgoing field (*i.e.* any field with v_(â) ≥ 0).
- At internal boundaries (i.e. interfaces between computational subdomains) use outgoing characteristics of one subdomain to fix data for incoming characteristics of neighboring subdomain.

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- For suitably large *k* the linearized evolution system becomes: $\partial_t \delta u^{\alpha} + A^{k \alpha}{}_{\beta} \partial_k \delta u^{\beta} \approx -i \left(\omega \delta^{\alpha}{}_{\beta} - k n_k A^{k \alpha}{}_{\beta} \right) V^{\beta} \approx 0.$

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- If V^α = S^{αβ}e^â_β is one of the eigenvectors of n_kA^{kα}_β with eigenvalue v_(â), then the short wavelength dispersion relation for this perturbation becomes: ω = k v_(â) for this perturbation.

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- If V^α = S^{αβ}e^â_β is one of the eigenvectors of n_kA^{kα}_β with eigenvalue v_(â), then the short wavelength dispersion relation for this perturbation becomes: ω = k v_(â) for this perturbation.
- The phase velocity of this perturbation is just the characteristic speed v_(â).
 - If v_(â) < 0, this represents an incoming perturbation that requires a boundary condition.
 - If v_(â) ≥ 0, this represents an outgoing wave that is determined completely by the fields inside the boundary, so no boundary condition is allowed.

• Consider the scalar field equation $\nabla^a \nabla_a \psi = 0$ on a spacetime with fixed metric $ds^2 = -N^2 dt^2 + g_{ij}(dx^i + N^i dt)(dx^j + N^j dt)$. The first order form of this system (including constraint damping):

$$\partial_t \psi - N^k (1 + \gamma_1) \partial_k \psi \simeq 0,$$

$$\partial_t \Pi - N^k \partial_k \Pi + N g^{ki} \partial_k \Phi_i \simeq 0,$$

$$\partial_t \Phi_i - N^k \partial_k \Phi_i + N \partial_i \Pi - \gamma_2 N \partial_i \psi \simeq 0.$$

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$$\partial_t \psi - N^{\kappa} (1 + \gamma_1) \partial_k \psi \simeq 0,$$

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• The characteristic fields $u^{\hat{\alpha}} = e^{\hat{\alpha}}_{\beta}u^{\beta}$ for this system consist of the fields $u^{\hat{\alpha}} = \{u^{\hat{0}}, u^{\hat{1}\pm}, u^{\hat{2}}_{i}\}$, given by $u^{\hat{0}} = \psi, \qquad u^{\hat{1}\pm} = \Pi \pm n^{k}\Phi_{k} - \gamma_{2}\psi, \qquad u^{\hat{2}}_{i} = (\delta^{k}_{i} - n^{k}n_{i})\Phi_{k},$

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The coordinate characteristic speeds associated with these fields are v_(0̂) = -(1+γ₁)n_kN^k for the field u^{0̂}, v_(1̂±) = -n^kN_k ± N for the fields u^{1̂±}, and v_(2̂) = -n_kN^k for the fields u^{2̂}.

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the fields u^{1±}, and v₍₂₎ = -n_kN^k for the fields u²_i.
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The characteristic fields u^{α̂} = e^ô_βu^β for the generalized harmonic version of the Einstein evolution equations look very much like their scalar field counterparts: u^{α̂} = {u^{0̂}_{ab}, u^{1̂±}_{ab}, u^{2̂}_{iab}}, given by

$$\begin{split} u_{ab}^{\hat{0}} &= \psi_{ab}, \\ u_{ab}^{\hat{1}\pm} &= \Pi_{ab} \pm n^k \Phi_{kab} - \gamma_2 \psi_{ab}, \\ u_{iab}^{\hat{2}} &= (\delta_i^k - n^k n_i) \Phi_{kab}, \end{split}$$

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• The coordinate characteristic speeds associated with these fields also have the same forms as those for the scalar field system: $v_{(\hat{0})} = -(1+\gamma_1)n_kN^k$ for the fields $u_{ab}^{\hat{0}}$, $v_{(\hat{1}\pm)} = -n^kN_k \pm N$ for the fields $u_{ab}^{\hat{1}\pm}$, and $v_{(\hat{2})} = -n_kN^k$ for the fields $u_{iab}^{\hat{2}}$.

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- A boundary condition must be imposed on each characteristic field whose characteristic speed is negative on that boundary.
- A boundary condition may not be imposed on any characteristic field whose characteristic speed is non-negative on that boundary.

Evolutions of a Perturbed Schwarzschild Black Hole

 The simplest boundary conditions that correspond (roughly) to "no incoming waves" set u^{α̂} = 0 for each incoming field, or
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- A black-hole spacetime is perturbed by an outgoing gravitational wave.
- Use boundary conditions that *Freeze* the incoming characteristic fields: $d_t u^{\hat{\alpha}} = 0$.
- The outgoing waves interact with the boundary of the computational domain and produce constraint violations.



• Construct the characteristic fields, $\hat{c}^{\hat{A}} = e^{\hat{A}}_{A}c^{A}$, associated with the constraint evolution system, $\partial_{t}c^{A} + A^{kA}_{B}\partial_{k}c^{B} = F^{A}_{B}c^{B}$.

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$$d_{\perp}\hat{u}^{-}=-\hat{F}(u,d_{\parallel}u).$$

Constraint Characteristic Fields

 The characteristic fields associated with the constraint evolution system, and their associated characteristic speeds for the first-order Einstein system are:

$$\begin{array}{lll} c_a^{\hat{0}\pm} &=& \mathcal{F}_a \mp n^k \mathcal{C}_{ka} \approx t^c \partial_c \mathcal{C}_a \mp n^k \partial_k \mathcal{C}_a, & v_{(\hat{0}\pm)} = -n_k N^k \pm N, \\ c_a^{\hat{1}} &=& \mathcal{C}_a, & v_{(\hat{1})} = 0, \\ c_{ia}^{\hat{2}} &=& P^k{}_i \mathcal{C}_{ka} \approx (\delta^k{}_i - n^k n_i) \partial_k \mathcal{C}_a, & v_{(\hat{2})} = -n_k N^k, \\ c_{iab}^{\hat{3}} &=& \mathcal{C}_{iab}, & v_{(\hat{3})} = -(1 + \gamma_1) n_k N^k, \\ c_{ijab}^{\hat{4}} &=& \mathcal{C}_{ijab} = 2 \partial_{[j} \mathcal{C}_{i]ab}, & v_{(\hat{4})} = -n_k N^k. \end{array}$$

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• The constraint characteristic fields $c_a^{\hat{0}-}$, $c_{iab}^{\hat{3}}$ and $c_{ijab}^{\hat{4}}$ have the same characteristic speeds as the principal dynamical fields $u_{ab}^{\hat{1}-}$, $u_{ab}^{\hat{0}}$ and $u_{iab}^{\hat{2}}$ respectively. These constraint fields will be incoming under the same conditions as these dynamical fiels.

Constraint Characteristic Fields II

Fortunately, the incoming constraint characteristic fields, c⁰⁻_a, c³_{iab} and c⁴_{ikab}, can be expressed in terms of the corresponding principal dynamical characteristic fields:

$$\begin{array}{lll} c_a^{\hat{0}-} &\approx & \sqrt{2} \left[k^{(c} \psi^{d)}_{a} - \frac{1}{2} k_a \psi^{cd} \right] d_{\perp} u_{cd}^{\hat{1}-}, \\ n^k c_{kab}^{\hat{3}} &\approx & d_{\perp} u_{ab}^{\hat{0}}, \\ n^k c_{kiab}^{\hat{4}} &\approx & d_{\perp} u_{iab}^{\hat{2}}, \end{array}$$

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 Setting these incoming characteristic constraint fields to zero therefore provides boundary conditions on the normal derivatives d_⊥u^{α̂} = e^{α̂}_βn^k∂_ku^β of some of the primary dynamical characteristic fields.

Physical Boundary Conditions

- The Weyl curvature tensor C_{abcd} satisfies a system of evolution equations from the Bianchi identities: $\nabla_{[a}C_{bc]de} = 0$.
- The characteristic fields of this system corresponding to physical gravitational waves are the quantities:

 $\hat{w}_{ab}^{\pm} = (P_a{}^c P_b{}^d - {}_{\frac{1}{2}}\dot{P}_{ab}P^{cd})(t^e \mp n^e)(t^f \mp n^f)C_{cedf},$

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• The incoming field \hat{w}_{ab}^- can be expressed in terms of the characteristic fields of the primary evolution system:

$$\hat{w}_{ab}^{-} = d_{\perp}u_{ab}^{\hat{1}-} + \hat{F}_{ab}(u, d_{\parallel}u).$$

• We impose boundary conditions on the physical graviational wave degrees of freedom then by setting:

$$d_\perp u_{ab}^{\hat{1}-} = -\hat{\mathcal{F}}_{ab}(u,d_\parallel u) + \hat{w}_{ab}^-|_{t=0}.$$

• Consider Neumann-like boundary conditions of the form $e^{\hat{\alpha}}_{\beta}n^{k}\partial_{k}u^{\beta} \equiv d_{\perp}u^{\hat{\alpha}} = d_{\perp}u^{\hat{\alpha}}|_{BC}.$

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- The spatial derivatives of u^{γ} in this expression can be re-written: $e^{\hat{\alpha}}_{\beta}A^{k}{}^{\beta}_{\gamma}\partial_{k}u^{\gamma} = v_{(\hat{\alpha})}e^{\hat{\alpha}}{}_{\gamma}n^{k}\partial_{k}u^{\gamma} + e^{\hat{\alpha}}{}_{\beta}A^{\ell}{}^{\beta}{}_{\gamma}(\delta^{k}{}_{\ell} - n^{k}n_{\ell})\partial_{k}u^{\gamma}.$

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- We impose these Neumann-like boundary conditions by changing the appropriate components of the evolution equations at the boundary to:

$$d_t u^{\hat{\alpha}} = D_t u^{\hat{\alpha}} + v_{(\hat{\alpha})} \big(d_{\perp} u^{\hat{\alpha}} - d_{\perp} u^{\hat{\alpha}} |_{\mathrm{BC}} \big).$$