

# Solving the Inverse Stellar Structure Problem

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- How can the equation of state of the matter in a star be determined from astronomical observations?
- This talk will focus on exploring the mathematical, rather than observational, aspects of this question.

# Relativistic Stellar Structure Problem (SSP)

- Given an equation of state,  $\epsilon = \epsilon(p)$ , solve Einstein's equations,

$$\frac{dm}{dr} = 4\pi r^2 \epsilon,$$

$$\frac{dp}{dr} = -(\epsilon + p) \frac{m + 4\pi r^3 p}{r(r - 2m)},$$

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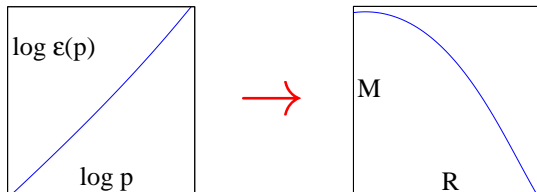
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to determine the structures of relativistic stars.

- Find the radius  $\rho(R) = 0$  and mass  $M = m(R)$  for each star.
- SSP can be thought of as a map from the equation of state  $\epsilon = \epsilon(\rho)$  to the M-R curve  $\{R(\rho_c), M(\rho_c)\}$ .

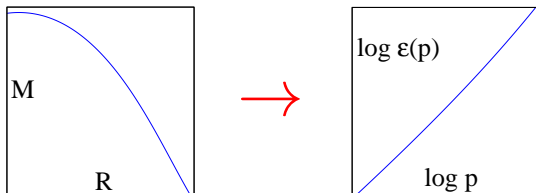


# Relativistic Inverse Stellar Structure Problem (SSP<sup>-1</sup>)

- When the equation of state is well understood – as in white dwarf stars – the standard stellar structure problem is useful.
- When the equation of state is poorly known – as in neutron stars – the inverse stellar structure problem (SSP<sup>-1</sup>) is more interesting.

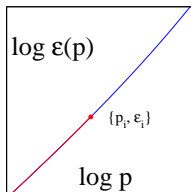
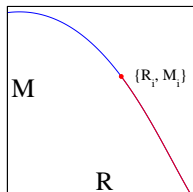
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- SSP<sup>-1</sup> finds the equation of state  $\epsilon = \epsilon(p)$  from a given mass-radius curve.
- SSP<sup>-1</sup> can be thought of as the map from the M-R curve  $\{R(p_c), M(p_c)\}$  to the equation of state  $\epsilon = \epsilon(p)$ .



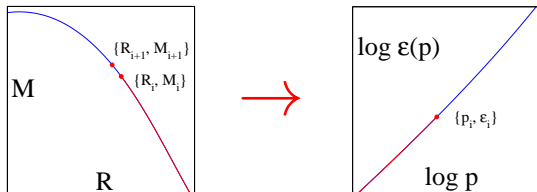
# Standard Solution to SSP<sup>-1</sup>

- Assume the complete M-R curve is known, including the point  $\{R_i, M_i\} = \{R(p_i), M(p_i)\}$ .
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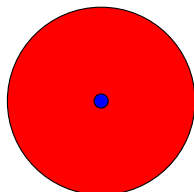
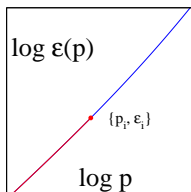
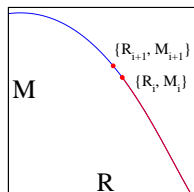


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- Choose a new point on the M-R curve,  $\{R_{i+1}, M_{i+1}\}$ , having slightly larger central density.
- Integrate Einstein's equations,

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dp}{dr} = -(\epsilon + p) \frac{m + 4\pi r^3 p}{r(r - 2m)},$$

through the outer parts of the star, to determine the mass and radius,  $\{r_{i+1}, m_{i+1}\}$ , of the small core with large densities  $\epsilon \geq \epsilon_i$ .

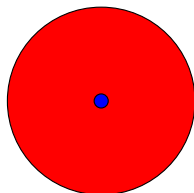
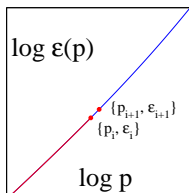
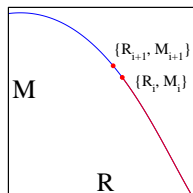
## Standard Solution to SSP<sup>-1</sup> II

- For very small cores,  $\{r_{i+1}, m_{i+1}\}$ , the solution to the OV equations is described by the power series solution:

$$m_{i+1} = \frac{4\pi}{3} \epsilon_{i+1} r_{i+1}^3 + \mathcal{O}(r_{i+1}^5),$$

$$p_i = p_{i+1} - \frac{2\pi}{3} (\epsilon_{i+1} + p_{i+1})(\epsilon_{i+1} + 3p_{i+1}) r_{i+1}^2 + \mathcal{O}(r_{i+1}^4).$$

- Invert these series to determine the central pressure and density,  $\{p_{i+1}, \epsilon_{i+1}\}$ , in terms of the known quantities,  $p_i, \epsilon_i, m_{i+1}, r_{i+1}$ .



# Can the Standard Solution to SSP<sup>-1</sup> be Improved?

- Standard solution to the relativistic SSP<sup>-1</sup> finds the equation of state,  $\epsilon = \epsilon(\rho)$ , represented as a table:  $\{\rho_i, \epsilon_i\}$  for  $i = 1, \dots, N$ .
- Standard solution has several weaknesses:
  - Solution converges (slowly) with the number of points, as  $N^{-p}$ .
  - Each new equation of state point,  $\{\rho_i, \epsilon_i\}$ , requires the knowledge of a separate new M-R curve point,  $\{R_i, M_i\}$ .
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- Spectral numerical methods typically converge more rapidly, and represent functions more efficiently than finite difference methods.
- Can spectral methods provide better (*i.e.* more practical and more accurate) solutions to the  $SSP^{-1}$ ?
- Can spectral methods provide interesting solutions to  $SSP^{-1}$  when only a few (*e.g.* two or three) M-R data points are available?

# Outline for Solving $SSP^{-1}$ Using Spectral Methods

- Assume the equation of state can be written in the form  $\epsilon = \epsilon(\rho, \gamma_k)$ , where the  $\gamma_k$  are a set of parameters.

For example, the equation of state could be written as a spectral expansion,  $\epsilon = \epsilon(\rho, \gamma_k) = \sum_k \gamma_k \Phi_k(\rho)$ , where the  $\Phi_k(\rho)$  are spectral basis functions, e.g.  $\Phi_k(\rho) = e^{ik\rho}$ , or  $\Phi_k(\rho) = P_k(\rho)$ .

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- Given a set of points from the “real” M-R curve,  $\{R_i, M_i\}$ , choose the parameters  $\gamma_k$  and  $\mathbf{p}_i$  that minimize the difference measure:

$$\chi^2 = \frac{1}{N_{\text{stars}}} \sum_{i=1}^{N_{\text{stars}}} \left\{ \left[ \log \left( \frac{R(\mathbf{p}_i, \gamma_k)}{R_i} \right) \right]^2 + \left[ \log \left( \frac{M(\mathbf{p}_i, \gamma_k)}{M_i} \right) \right]^2 \right\}$$



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- Resulting  $\gamma_k$  for  $k = 1, \dots, N_{\gamma_k}$  determines an equation of state,  $\epsilon = \epsilon(\mathbf{p}, \gamma_k)$ , that provides an approximate solution of  $SSP^{-1}$ .

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- These questions are best answered using a somewhat different form of the standard stellar structure problem (SSP).
- Digress (briefly) now to describe this alternate formulation that provides a more efficient and more accurate way to solve the SSP.

# Alternative Representations of the SSP

- The standard Oppenheimer-Volkoff (OV) representation of the SSP equations determines  $m(r)$  and  $p(r)$ , given an equation of state of the form  $\epsilon = \epsilon(p)$ .
- The outer boundary of the star is the point where  $p(R) = 0$ . This condition is difficult to solve numerically because the pressure goes to zero non-linearly there:  $p \propto (R - r)^{\Gamma_0/(\Gamma_0 - 1)}$ .

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- This problem can be simplified by introducing the relativistic enthalpy  $h(p) = \int_0^p dp' / [\epsilon(p') + p']$ , and re-writing the OV equations in terms of it:

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- The surface of the star is now the point where  $h(R) = 0$ . This condition is easier to solve numerically because the enthalpy goes to zero linearly there:  $h(r) \propto (R - r)$ .

## Alternative Representations of the SSP II

- Simplify again by swapping the roles of  $h$  and  $r$ :

$$\frac{dm}{dh} = -\frac{4\pi\epsilon(h)r^3(r-2m)}{m+4\pi r^3\rho(h)}, \quad \frac{dr}{dh} = -\frac{r(r-2m)}{m+4\pi r^3\rho(h)}.$$



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- These alternative OV equations require that the equation of state,  $\epsilon = \epsilon(p)$ , be re-written as  $\epsilon = \epsilon(h)$  and  $p = p(h)$ :
  - Start with the standard,  $\epsilon = \epsilon(p)$ .
  - Compute,  $h(p) = \int_0^p dp' / [\epsilon(p') + p']$ .
  - Invert to give  $p = p(h)$ .
  - Compose  $\epsilon = \epsilon(p)$  with  $p = p(h)$ , to give  $\epsilon = \epsilon(h) = \epsilon[p(h)]$ .

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- Faithful here means *i)* that every choice of spectral parameters,  $\alpha_k$  and  $\beta_k$ , corresponds to a possible physical equation of state, and *ii)* that every equation of state can be represented by such an expansion.

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$$\frac{dp}{dh} = \epsilon + p, \quad \frac{d\epsilon}{dh} = \frac{(\epsilon + p)^2}{p\Gamma(h)}.$$

## Faithful Spectral Expansions of the Equation of State II

- Every equation of state is determined by the adiabatic index  $\Gamma(h)$ :

$$\frac{dp}{dh} = \epsilon + p, \quad \frac{d\epsilon}{dh} = \frac{(\epsilon + p)^2}{p\Gamma(h)}.$$

- The solutions to these equations can be reduced to quadratures:

$$\begin{aligned} p(h) &= p_0 \exp \left[ \int_{h_0}^h \frac{e^{h'}}{\mu(h')} dh' \right], \\ \mu(h) &= \frac{p_0 e^{h_0}}{\epsilon_0 + p_0} + \int_{h_0}^h \frac{\Gamma(h') - 1}{\Gamma(h')} e^{h'} dh', \\ \epsilon(h) &= p(h) \frac{e^h - \mu(h)}{\mu(h)}. \end{aligned}$$

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- Choosing,  $\log \Gamma(h) = \sum_k \gamma_k \Phi_k(h)$ , for any spectral basis functions,  $\Phi_k(h)$ , results in a faithful parametrized equation of state of the desired form:  $\epsilon = \epsilon(h, \gamma_k)$  and  $p = p(h, \gamma_k)$ .



# Fitting Model Neutron-Star Equations of State

- How accurately and efficiently are realistic neutron-star equations of state represented by  $\epsilon = \epsilon(h, \gamma_k)$  and  $p = p(h, \gamma_k)$ , when  $\Gamma(h)$  is given by

$$\Gamma(h) = \exp \left\{ \sum_{k=0}^{N_{\gamma_k}-1} \gamma_k \left[ \log \left( \frac{h}{h_0} \right) \right]^k \right\} ?$$

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- Let  $\{p_i, \epsilon_i, h_i\}$ , for  $i = 1, \dots, N_{\text{EOS}}$  denote one of the standard tabulated realistic neutron-star equations of state.
- Find the spectral parameters  $\gamma_k$  that minimize the fitting error:

$$\left( \Delta_{N_{\gamma_k}}^{\text{EOS}} \right)^2 = \frac{1}{N_{\text{EOS}}} \sum_{i=1}^{N_{\text{EOS}}} \left[ \log \left( \frac{\epsilon(h_i, \gamma_k)}{\epsilon_i} \right) \right]^2 .$$

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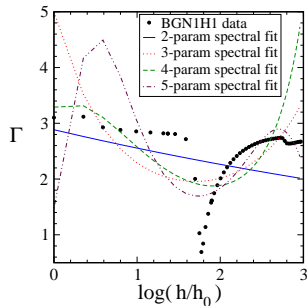
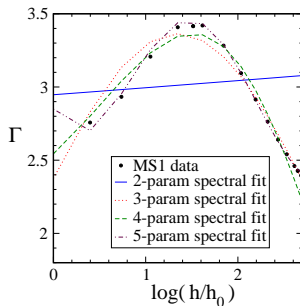
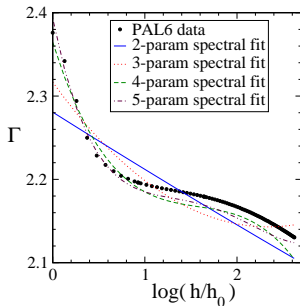
- Let  $\{p_i, \epsilon_i, h_i\}$ , for  $i = 1, \dots, N_{\text{EOS}}$  denote one of the standard tabulated realistic neutron-star equations of state.
- Find the spectral parameters  $\gamma_k$  that minimize the fitting error:

$$\left( \Delta_{N_{\gamma_k}}^{\text{EOS}} \right)^2 = \frac{1}{N_{\text{EOS}}} \sum_{i=1}^{N_{\text{EOS}}} \left[ \log \left( \frac{\epsilon(h_i, \gamma_k)}{\epsilon_i} \right) \right]^2 .$$

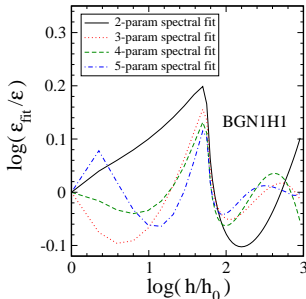
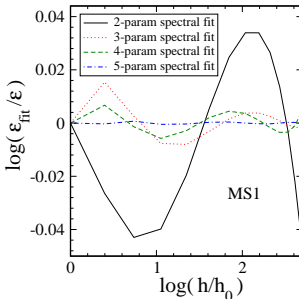
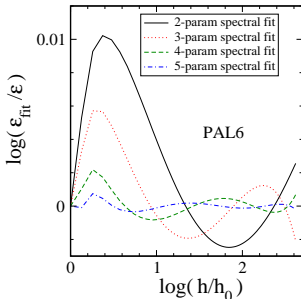
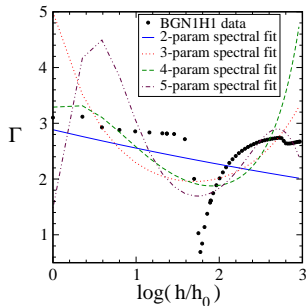
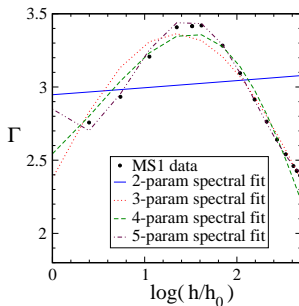
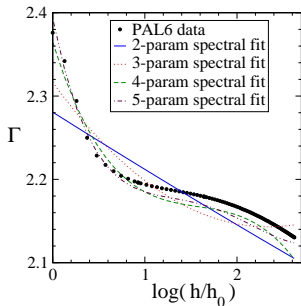
- The average values of these fitting errors,  $\Delta_{N_{\gamma_k}}^{\text{EOS}}$ , for 34 realistic neutron-star equations of state are:

$$\begin{aligned} \Delta_2^{\text{EOS}} &= 0.032, & \Delta_3^{\text{EOS}} &= 0.017, \\ \Delta_4^{\text{EOS}} &= 0.012, & \Delta_5^{\text{EOS}} &= 0.0089. \end{aligned}$$

# Spectral Fits of Model Neutron-Star Equations of State



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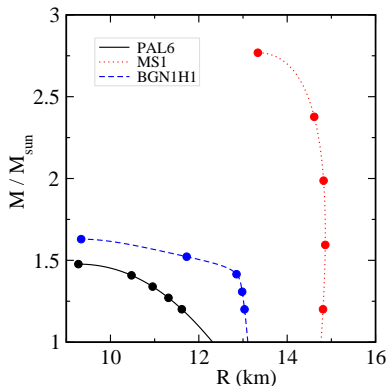


## Spectral Solution of $SSP^{-1}$

- Next step is to test this spectral approach to solving the  $SSP^{-1}$  using realistic neutron-star models.
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- Choose mock data points  $\{R_i, M_i\}$  for neutron-star models computed with 34 realistic equations of state.



## Spectral Solution of SSP<sup>-1</sup> II

- Fix the spectral expansion coefficients  $\gamma_k$  by minimizing,

$$\chi^2 = \frac{1}{N_{\text{stars}}} \sum_{i=1}^{N_{\text{stars}}} \left\{ \left[ \log \left( \frac{M(h_c^i, \gamma_k)}{M_i} \right) \right]^2 + \left[ \log \left( \frac{R(h_c^i, \gamma_k)}{R_i} \right) \right]^2 \right\}.$$

with respect to variations in  $\gamma_k$ , and variations in the central values of the enthalpy for each star,  $h_c^i$ .



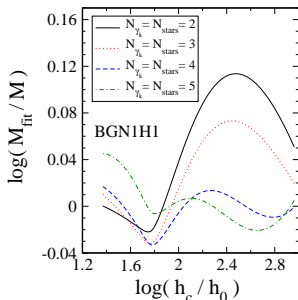
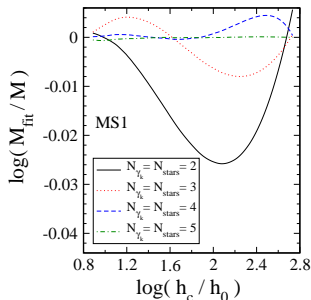
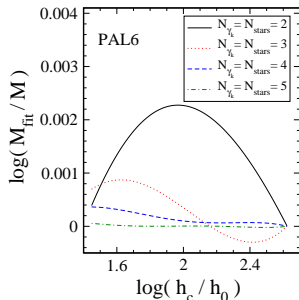
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with respect to variations in  $\gamma_k$ , and variations in the central values of the enthalpy for each star,  $h_c^i$ .

- Compare the resulting M-R curve  $\{R(h, \gamma_k), M(h, \gamma_k)\}$  with the exact curve from the known equation of state  $\{R(h), M(h)\}$ .



## Spectral Solutions to SSP<sup>-1</sup> III

- Next evaluate the equation of state fitting errors,  $\Delta_{N_{\gamma k}}^{MR}$ ,

$$\left(\Delta_{N_{\gamma k}}^{MR}\right)^2 = \frac{1}{N_{\text{EOS}}} \sum_{i=1}^{N_{\text{EOS}}} \left[ \log \left( \frac{\epsilon(h_i, \gamma_k)}{\epsilon_i} \right) \right]^2$$

to determine how well the spectral expansion  $\epsilon = \epsilon(h, \gamma_k)$ , matches the exact neutron-star equation of state  $\epsilon = \epsilon(h)$ .

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- The average values of  $\Delta_{N_{\gamma k}}^{MR}$  (with  $N_{\gamma k} = N_{\text{stars}}$ ) determined in this way for 34 realistic model equations of state are:

$$\begin{array}{ll} \Delta_2^{MR} = 0.039, & \Delta_2^{EOS} = 0.032, \\ \Delta_3^{MR} = 0.026, & \Delta_3^{EOS} = 0.017, \\ \Delta_4^{MR} = 0.017, & \Delta_4^{EOS} = 0.012, \\ \Delta_5^{MR} = 0.015, & \Delta_5^{EOS} = 0.0089. \end{array}$$

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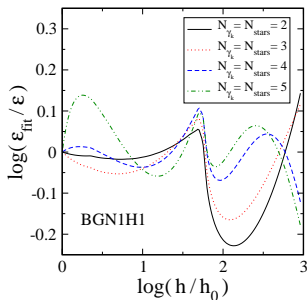
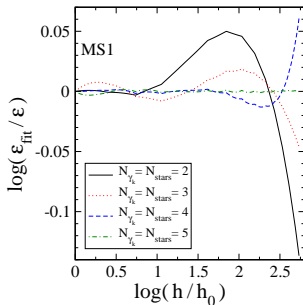
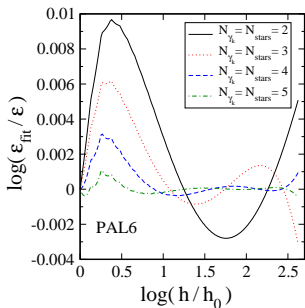
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- The accuracy of these solutions to the  $SSP^{-1}$  is quite impressive, even though the number of M-R data used is very small.
- The convergence of  $\Delta_{N_{\gamma k}}^{MR}$  is not as good as  $\Delta_{N_{\gamma k}}^{EOS}$ . Perhaps our  $\chi^2$  minimization finds local not global minima?

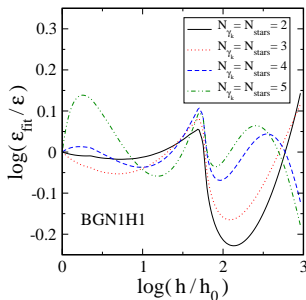
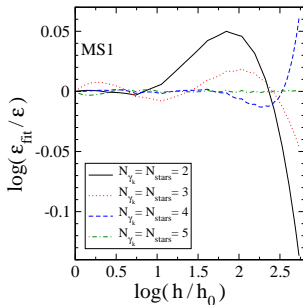
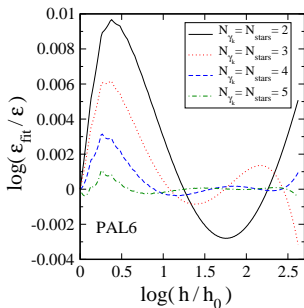
# Spectral Solutions to SSP<sup>-1</sup> IV

- Compare the spectral equation of state,  $\epsilon(h, \gamma_k)$ , determined by fitting the M-R data with the exact equation of state  $\epsilon(h)$ :



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- **Conclusion:** The spectral approach provides a very promising way to determine the neutron-star equation of state from observed properties of these stars.