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AMS Meeting :: New Orleans :: 7 January 2007

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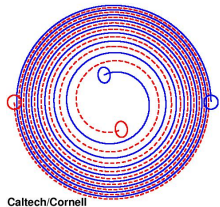
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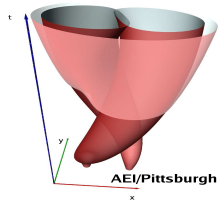
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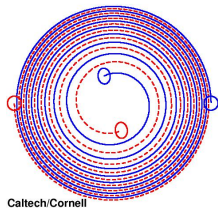
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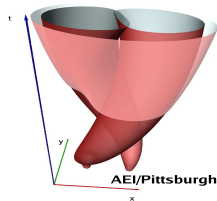
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- Frans Pretorius performed first numerical BBH inspiral, merger and ringdown calculations in 2005. Pretorius Inspiral Movies
- Caltech/Cornell collaboration and the AEI/Pittsburgh collaboration perform successful BBH simulations in 2006 using GH methods.
- Outline of this talk:
  - Review Generalized Harmonic (GH) form of the Einstein system.
  - Constraint damping.
  - Boundary conditions.

# Methods of Specifying Spacetime Coordinates

- We often decompose the 4-metric into its 3+1 parts:

$$ds^2 = \psi_{ab} dx^a dx^b = -N^2 dt^2 + g_{ij} (dx^i + N^i dt)(dx^j + N^j dt).$$

The lapse  $N$  and shift  $N^i$  specify how coordinates are laid out on a spacetime manifold:  $\vec{n} = \partial_\tau = (\partial_t - N^k \partial_k)/N$ .

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- An alternate way to specify the coordinates is through the gauge source function  $H^a$ :
- Let  $H^a$  denote the function obtained by the action of the covariant scalar wave operator on the coordinates  $x^a$ :

$$H^a \equiv \nabla^c \nabla_c x^a = -\Gamma^a,$$

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- Specifying coordinates by the *generalized harmonic* (GH) method can be accomplished by choosing a gauge-source function

$$H_a(x, \psi) = \psi_{ab} H^b, \text{ and requiring that}$$

$$H_a(x, \psi) = -\Gamma_a = -\psi_{ab} \psi^{cd} \Gamma^b_{cd}.$$

## Important Properties of the GH Method

- The Einstein equations are manifestly hyperbolic when coordinates are specified using a GH gauge function:

$$R_{ab} = -\frac{1}{2}\psi^{cd}\partial_c\partial_d\psi_{ab} + \nabla_{(a}\Gamma_{b)} + F_{ab}(\psi, \partial\psi),$$

where  $\psi_{ab}$  is the 4-metric, and  $\Gamma_a = \psi^{bc}\Gamma_{abc}$ . The vacuum Einstein equation,  $R_{ab} = 0$ , has the same principal part as the scalar wave equation when  $H_a(\mathbf{x}, \psi) = -\Gamma_a$  is imposed.



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- Imposing coordinates using a GH gauge function profoundly changes the constraints. The GH constraint,  $\mathcal{C}_a = 0$ , where

$$\mathcal{C}_a = H_a + \Gamma_a,$$

depends only on first derivatives of the metric. The standard Hamiltonian and momentum constraints,  $\mathcal{M}_a = 0$ , are determined by the derivatives of the gauge constraint  $\mathcal{C}_a$ :

$$\mathcal{M}_a \equiv \left[ R_{ab} - \frac{1}{2}\psi_{ab}R \right] n^b = \left[ \nabla_{(a}\mathcal{C}_{b)} - \frac{1}{2}\psi_{ab}\nabla^c\mathcal{C}_c \right] n^b.$$

# Constraint Damping Generalized Harmonic System

- Pretorius (based on a suggestion from Gundlach, et al.) modified the GH system by adding terms proportional to the gauge constraints:

$$0 = R_{ab} - \nabla_{(a} \mathcal{C}_{b)} + \gamma_0 \left[ n_{(a} \mathcal{C}_{b)} - \frac{1}{2} \psi_{ab} n^c \mathcal{C}_c \right],$$

where  $n^a$  is a unit timelike vector field. Since  $\mathcal{C}_a = H_a + \Gamma_a$  depends only on first derivatives of the metric, these additional terms do not change the hyperbolic structure of the system.

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- Evolution of the constraints  $\mathcal{C}_a$  follow from the Bianchi identities:

$$0 = \nabla^c \nabla_c \mathcal{C}_a - 2\gamma_0 \nabla^c [n_{(c} \mathcal{C}_{a)}] + \mathcal{C}^c \nabla_{(c} \mathcal{C}_{a)} - \frac{1}{2} \gamma_0 n_a \mathcal{C}^c \mathcal{C}_c.$$

This is a damped wave equation for  $\mathcal{C}_a$ , that drives all small short-wavelength constraint violations toward zero as the system evolves (for  $\gamma_0 > 0$ ).

# First Order Generalized Harmonic Evolution System

- **Kashif Alvi** (2002) derived a nice (symmetric hyperbolic) first-order form for the generalized-harmonic evolution system:

$$\begin{aligned}\Phi_{kab} &= \partial_k \psi_{ab}, \\ \partial_t \psi_{ab} - N^k \partial_k \psi_{ab} &= -N \Pi_{ab}, \\ \partial_t \Pi_{ab} - N^k \partial_k \Pi_{ab} + N g^{ki} \partial_k \Phi_{iab} &\simeq 0, \\ \partial_t \Phi_{iab} - N^k \partial_k \Phi_{iab} + N \partial_i \Pi_{ab} &\simeq 0.\end{aligned}$$

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- This system has two immediate problems:
  - This system has new constraints,  $\mathcal{C}_{kab} = \partial_k \psi_{ab} - \Phi_{kab}$ , that tend to grow exponentially during numerical evolutions.
  - This system is not linearly degenerate, so it is possible (likely) that shocks will develop (e.g. the shift evolution equation is of the form  $\partial_t N^i - N^k \partial_k N^i \simeq 0$ ).

# Improved First-Order GH Evolution System

- We can correct these problems by adding additional multiples of the constraints to the evolution system:

$$\partial_t \psi_{ab} - (1 + \gamma_1) N^k \partial_k \psi_{ab} = -N \Pi_{ab} - \gamma_1 N^k \Phi_{kab},$$

$$\partial_t \Pi_{ab} - N^k \partial_k \Pi_{ab} + N g^{ki} \partial_k \Phi_{iab} - \gamma_1 \gamma_2 N^k \partial_k \psi_{ab} \simeq -\gamma_1 \gamma_2 N^k \Phi_{kab},$$

$$\partial_t \Phi_{iab} - N^k \partial_k \Phi_{iab} + N \partial_j \Pi_{ab} - \gamma_2 N \partial_i \psi_{ab} \simeq -\gamma_2 N \Phi_{iab}.$$

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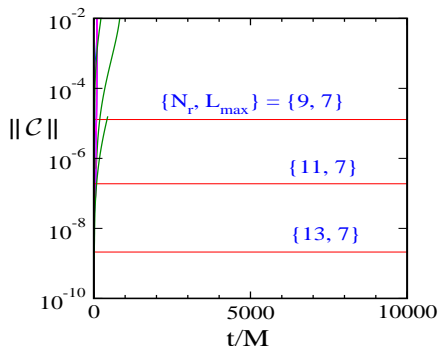
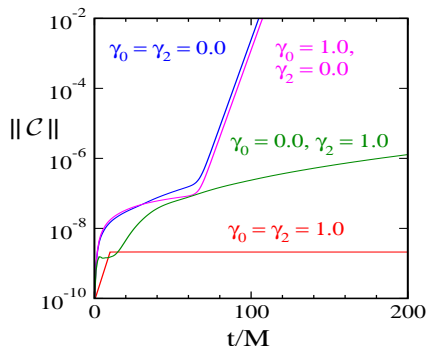
- We can correct these problems by adding additional multiples of the constraints to the evolution system:

$$\begin{aligned}\partial_t \psi_{ab} - (1 + \gamma_1) N^k \partial_k \psi_{ab} &= -N \Pi_{ab} - \gamma_1 N^k \Phi_{kab}, \\ \partial_t \Pi_{ab} - N^k \partial_k \Pi_{ab} + N g^{ki} \partial_k \Phi_{iab} - \gamma_1 \gamma_2 N^k \partial_k \psi_{ab} &\simeq -\gamma_1 \gamma_2 N^k \Phi_{kab}, \\ \partial_t \Phi_{iab} - N^k \partial_k \Phi_{iab} + N \partial_i \Pi_{ab} - \gamma_2 N \partial_i \psi_{ab} &\simeq -\gamma_2 N \Phi_{iab}.\end{aligned}$$

- This improved GH evolution system has several nice properties:
  - This system is linearly degenerate for  $\gamma_1 = -1$  (and so shocks should not form from smooth initial data).
  - The  $\Phi_{iab}$  evolution equation can be written in the form,  $\partial_t C_{iab} - N^k \partial_k C_{iab} \simeq -\gamma_2 N C_{iab}$ , so the new constraints are damped when  $\gamma_2 > 0$ .
  - This system is symmetric hyperbolic for all values of  $\gamma_1$  and  $\gamma_2$ .

# Numerical Tests of the First-Order GH System

- 3D numerical evolutions of static black-hole spacetimes illustrate the constraint damping properties of the GH evolution system.
- These evolutions are stable and convergent when  $\gamma_0 = \gamma_2 = 1$ .



- The boundary conditions used for this simple test problem freeze the incoming characteristic fields to their initial values.



## Boundary Conditions

- Boundary conditions are straightforward to formulate for first-order hyperbolic evolutions systems,

$$\partial_t u^\alpha + A^{k\alpha}{}_\beta(u) \partial_k u^\beta = F^\alpha(u).$$

For the GH system  $u^\alpha = \{\psi_{ab}, \Pi_{ab}, \Phi_{kab}\}$ .

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- Find the eigenvectors of the characteristic matrix  $s_k A^{k\alpha}{}_\beta$  at each boundary point:

$$e^{\hat{\alpha}}{}_\alpha s_k A^{k\alpha}{}_\beta = v_{(\hat{\alpha})} e^{\hat{\alpha}}{}_\beta,$$

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- For hyperbolic evolution systems the eigenvectors  $e^{\hat{\alpha}}{}_\alpha$  are complete:  $\det e^{\hat{\alpha}}{}_\alpha \neq 0$ . So we define the characteristic fields:

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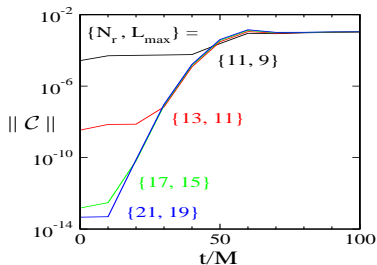
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- A boundary condition must be imposed on each incoming characteristic field (*i.e.* every field with  $v_{(\hat{\alpha})} < 0$ ), and must not be imposed on any outgoing field (*i.e.* any field with  $v_{(\hat{\alpha})} > 0$ ).

# Evolutions of a Perturbed Schwarzschild Black Hole

- A black-hole spacetime is perturbed by an incoming gravitational wave that excites quasi-normal oscillations.
- Use boundary conditions that *Freeze* the remaining incoming characteristic fields.
- The resulting outgoing waves interact with the boundary of the computational domain and produce constraint violations.



Lapse Movie

Constraint Movie

# Constraint Evolution for the First-Order GH System

- The evolution of the constraints,

$\mathbf{c}^A = \{C_a, C_{kab}, \mathcal{M}_a \approx n^c \partial_c C_a, C_{ka} \approx \partial_k C_a, C_{klab} = \partial_{[k} \Phi_{l]ab}\}$  are determined by the evolution of the fields  $u^\alpha = \{\psi_{ab}, \Pi_{ab}, \Phi_{kab}\}$ :

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- This constraint evolution system is symmetric hyperbolic with principal part:

$$\begin{aligned} \partial_t C_a &\simeq 0, \\ \partial_t \mathcal{M}_a - N^k \partial_k \mathcal{M}_a - N g^{ij} \partial_i C_{ja} &\simeq 0, \\ \partial_t C_{ia} - N^k \partial_k C_{ia} - N \partial_i \mathcal{M}_a &\simeq 0, \\ \partial_t C_{iab} - (1 + \gamma_1) N^k \partial_k C_{iab} &\simeq 0, \\ \partial_t C_{ijab} - N^k \partial_k C_{ijab} &\simeq 0. \end{aligned}$$

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- An analysis of this system shows that all of the constraints are damped in the WKB limit when  $\gamma_0 > 0$  and  $\gamma_2 > 0$ . So, this system has constraint suppression properties that are similar to those of the Pretorius (and Gundlach, et al.) system.



# Constraint Preserving Boundary Conditions

- Construct the characteristic fields,  $\hat{c}^{\hat{A}} = e^{\hat{A}}_A c^A$ , associated with the constraint evolution system,  $\partial_t c^A + A^k A^A_B \partial_k c^B = F^A_B c^B$ .

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- The constraints depend on the primary evolution fields (and their derivatives). We find that  $\hat{c}^-$  for the GH system can be expressed:

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- Set boundary conditions on the fields  $\hat{u}^-$  by requiring

$$d_{\perp} \hat{u}^- = -\hat{F}(u, d_{\parallel} u).$$

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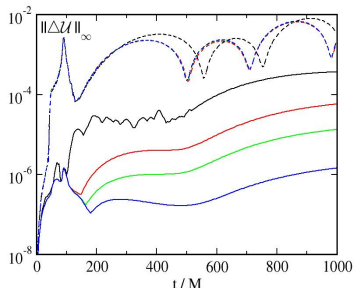
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- Oliver Rinne (2006) used Fourier-Laplace analysis to show that these BC satisfy the Kreiss (1970) condition which is necessary for well-posedness (but not sufficient for this type of BC).
- **Help Wanted!** New analysis methods are needed to prove (or disprove) complete well-posedness for this type of BC.

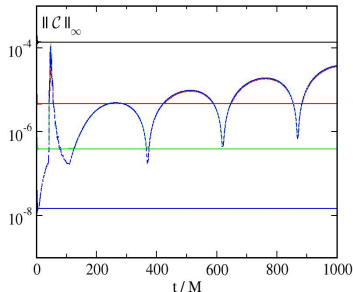
# Numerical Tests of Boundary Conditions

- Compare the solution obtained on a “small” computational domain with a reference solution obtained on a “large” domain where the boundary is not in causal contact with the comparison region.

## Solution Differences



## Constraints



- Solutions using “Freezing” BC (dashed curves) have differences and constraints that do not converge to zero.
- Solutions using constraint preserving and physical BC (solid curves) have much smaller differences and constraints that converge to zero.

# Summary

- Generalized Harmonic method produces manifestly hyperbolic representations of the Einstein equations for any choice of coordinates.
- Constraint damping makes the modified GH equations stable for numerical simulations.
- Constraint preserving boundary conditions have been implemented and tested for the GH system.
- Binary black hole simulations have been successfully performed using GH methods by several groups using very different numerical methods.